The Alto Tiberina Near Fault Observatory (northern Apennines, Italy)

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ABSTRACT

The availability of multidisciplinary and high-resolution data is a fundamental requirement to understand the physics of earthquakes and faulting. We present the Alto Tiberina Near Fault Observatory (TABOO), a research infrastructure devoted to studying preparatory processes, slow and fast deformation along a fault system located in the upper Tiber Valley (northern Apennines), dominated by a 60 km long low-angle normal fault (Alto Tiberina, ATF) active since the Quaternary. TABOO consists of 50 permanent seismic stations covering an area of 120 × 120 km². The surface seismic stations are equipped with 3-components seismometers, one third of them hosting accelerometers. We instrumented three shallow (250 m) boreholes with seismometers, creating a 3-dimensional antenna for studying micro-earthquakes sources (detection threshold is ML 0.5) and detecting transient signals. 24 of these sites are equipped with continuous geodetic GPS, forming two transects across the fault system. Geochemical and electromagnetic stations have been also deployed in the study area. In 36 months TABOO recorded 19,422 events with ML ≤ 3.8 corresponding to 23.36e-04 events per day per squared kilometres; one of the highest seismicity rate value observed in Italy. Seismicity distribution images the geometry of the ATF and its antithetic/synthetic structures located in the hanging-wall. TABOO can allow us to understand the seismogenic potential of the ATF and therefore contribute to the seismic hazard assessment of the area. The collected information on the geometry and deformation style of the fault will be used to elaborate ground shaking scenarios adopting diverse slip distributions and rupture directivity models.

1. Introduction: A natural laboratory

Crustal faults are complex natural systems whose mechanical properties evolve with time. Thus, the understanding of the multi-scale physical-chemical processes responsible for earthquakes and faulting requires considering phenomena at the boundaries between different research fields (road of integration) and the availability of long time series of high-resolution data.

With this aim we have been working for the past five years in the creation of what we called a Near Fault Observatory (NFO), consisting of a multidisciplinary research infrastructure based on state of the art observational systems continuously recording high quality data related to the underlying tectonic processes over a broad time interval. Such methodological approach based on an extremely high spatial resolution can be more easily applied at the local scale.

There are four main requirements for an area to be a suitable candidate as NFO: 1) it has to host active faults; 2) it has to be relatively small in terms of spatial scale (determined by the fault dimensions); 3) it must be characterised by a relatively high seismicity rate and 4) it has to be instrumented with multidisciplinary monitoring systems.

The area we selected as natural laboratory is located along the upper Tiber Valley within the inner sector of the northern Apennines (inset of Figure 1). According to the interpretation of few hundreds of kilometres of seismic reflection profiles [Pialli et al. 1998, Mirabella et al. 2011], the existence of a 60 km long extensional fault system active in the Quaternary and dominated at depth by an east-dipping low angle normal fault (dip 15°-25°), named Alto Tiberina Fault (ATF) [Barchi et al. 1998, Boncio et al. 2000], is documented in this area. The ATF...
bounds the western flank of the high Tiber Quaternary basin and has accumulated a minimum time-averaged long-term slip rate of about 1-3 mm/year in the last 2 Myr [Collettini and Holdsworth 2004, Mirabella et al. 2011] without large historical events unambiguously associated with this fault. Whilst, a set of synthetic and antithetic high angle faults that generated moderate events both in historical and instrumental epoch (Figure 1A) are located in the hanging-wall of the ATF. The NFO is devoted to the identification and understanding of the short- versus long-term deformation processes linked to the seismic and/or aseismic activity along this normal fault system. The presence of very high fluids (mostly CO₂) pressure (85% of the lithostatic load) at 4-5 km of depth, further motivated the deployment of this observing system.

We have initiated the construction of this research infrastructure in 2009 relying on both INGV (Istituto Nazionale di Geofisica e Vulcanologia) dedicated resources and Italian and European projects funding. In order to optimize the data acquisition, the new deployed monitoring stations have been built complementarily to the existing stations of the INGV national and regional seismic and geodetic networks. The network is now totally up and running [Monachesi et al. 2013], covering a 120 × 120 km² zone surrounding the ATF system (shaded area in Figure 1A).

In the following we describe the ATF Near Fault Observatory and the researches that we plan to perform with this observing system.

2. Scientific rationales

The earthquake recurrence models based on historical seismicity might involve large uncertainties due to sparse or incomplete information on large magnitude earthquakes and their association with a specific fault system, particularly when applied at local scale. In these circumstances, the analysis of micro-seismicity represents a unique tool to investigate the seismicity pattern and identify active tectonic structures. The joint investigation of seismicity and tectonic deformation through geodetic measurements and geological observations represents an effective approach to identify small- and large-scale tectonic processes. This requires the deployment of dense networks of instruments to enhance the detection power and increase the resolution of the observing system. The increased capability to detect signals from active tectonic processes occurring in the crust surrounding the investigated fault sys-

Figure 1. Map of the study area located in the inner sector of the northern Apennines (see inset on the right). (A) Largest historical and instrumental seismicity of the area. The red squares (scaled with magnitude; Rovida et al. [2011]) represent the macro-seismic location of the largest events occurred in the past 1000 years. Grey points represent the epicentral location (from the catalogue of the INGV national network available at: http://iside.rm.ingv.it/iside/standard/index.jsp) of the earthquakes occurred in between 1995-2010. The inset on the left shows the magnitude distribution for this catalogue with completeness around M 1.5. The blue stars and beach balls are the locations of the largest instrumental earthquakes and focal mechanism solutions, respectively. See text for details. The light blue box represents the projection at surface of the Alto Tiberina fault plane (after Mirabella et al. [2011]). (B) Map of the station distribution and location of the already existing deep boreholes. See text for explanation. The shaded line is the cross section trace of Figure 2.
It is worth noting that the micro-seismicity nucleating along the ATF is not able to explain the deformation associated with the short- and long-term slip rate inferred by geological [Collettini and Holdsworth 2004] and geodetic studies [D’Agostino et al. 2009], respectively. These observations together with the lack of a large magnitude historical earthquake [Rovida et al. 2011, and reference therein] that in the past 1000 years may have ruptured the whole ATF length (i.e. M 7), suggest the presence of aseismic deformation and creeping fault behaviour, as proposed by Hreinsdóttir and Bennett [2009] investigating regional GPS data. This behaviour would be coherent with the observation that no moderate-to-large magnitude earthquakes have been documented worldwide on low angle normal faults (LANF) using positively discriminated focal mechanisms [Jackson and White 1989, Collettini and Sibson 2001]. This is the reason why LANFs have been considered unimportant structures in terms of seismic hazard. On the contrary Finocchio et al. [2013] by means of a 2D elastoplastic finite-element model reproducing the very large scale interseismic deformation pattern observed by GPS data, propose an ATF completely locked.

The seismogenic potential of LANF is indeed still debated in the literature [Jackson and White 1989, Buck 1993, Westaway 1999, Collettini and Sibson 2001, Collettini 2011]. LANFs are faults characterized by very low dip angles (<30°). According to classical fault mechanics (i.e., faults in an elastic crust obeying Coulomb friction) these structures should not exist in extensional environments characterized by an Andersonian stress field (vertical maximum principal stress; Anderson [1951]), and fault static friction within the Byerlee’s 1978 range (0.6 < μs < 0.85; Byerlee [1978]). Contrary to this theoretical expectation, many field-based studies [Lister and Davis 1989, Axen 1999, Collettini and Holdsworth 2004] and the interpretation of seismic reflection profiles [e.g. Floyd et al. 2001] indicate that the LANFs can be tectonically active and generate earthquakes [Abers 1991, Wernicke 1995, Rigo et al. 1996, Abers et al. 1997, Axen 1999, Chiaraluce et al. 2007].

An additional motivation for building a NFO in this sector of the Apennines is the presence of deep fluid circulation, which makes the ATF an ideal site for studying the relationship between fluids, seismicity patterns and faulting. Several authors have investigated the seismicity pattern characterising the main seismic sequences occurred in this sector of the Apennines, and one of the main outcomes is that the prolonged aftershocks sequences can be explained in terms of subsequent earthquake failures promoted by fluid flow [Miller et al. 2004, Antonioli et al. 2005, Chiarabba et al. 2009]. The existence of fluid diffusion processes is

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supported by the evidence that, within two deep boreholes drilled in the study area and located in the ATF footwall (Pieve Santo Stefano and San Donato; Figure 1B), fluid overpressure (CO₂) at about 85% of lithostatic load has been encountered. In addition, the isotopic signature of a large number of local springs, indicates that the whole area is interested by an extremely large flux of CO₂ from a deep source [Chiodini et al. 2004].

The overpressurization from below of the crustal geological structures of the area, fed by mantle derived CO₂, is proposed as one of the primary triggering mechanisms of Apennine earthquakes [Chiodini et al. 2004].

For all these scientific objectives, we decided to deploy a multidisciplinary high-resolution observing system with the perspective of building a permanent research infrastructure: the TABOO Near Fault Observatory. This will represent a novel research framework to tackle the challenge of bridging the gap between natural processes observed in the fields (through seismological, geological and geodetic observations) and those observed in laboratory experiments on rock samples from exhumed faults. This is an added value in term of scientific perspective. These investigations will also contribute to better understand the seismogenic potential of the ATF, therefore contributing to the comprehension of seismic hazard in the study area. Last but not least, the NFO will provide the opportunity to implement and design the evolution of monitoring infrastructures and processing tools to build new services for ground-breaking researches.

3. Seismotectonic setting of the area

The study area is located at the Tuscany–Umbria–Marche regions boundary within the northern Apennines (Figure 1), a NE-verging thrust-fold belt undergoing NE-trending extension at a rate of about 3 mm/yr [Serpelloni et al. 2005, D’Agostino et al. 2009]. The extension is concentrated in the inner zone of the chain where the strongest historical (MCS intensity ≥ 8 X) and instrumental (5.0< M < 6.0) earthquakes are located (Figure 1A). The seismicity does not follow the arc shape structures inherited from the previous compressional tectonic phase but clusters along an about 20-30 km wide longitudinal zone [Chiaraluce et al. 2004, Chiarabba et al. 2005].

Three main earthquakes hit the area in past 20 years (location and focal mechanisms in Figure 1A). The southernmost is the 1997 Colfiorito Mw 6.0 earthquake with its sequence of moderate-magnitude events. Going north we find the 1998 Gualdo Tadino Mw 5.1 and the 1984 Gubbio Mw 5.1 events, respectively. All these earthquakes activated SW-dipping normal fault systems, thus antithetic to the ATF. The comparison of the 1984’s aftershocks distribution with background seismic activity of the area clearly shows how the Gubbio sequence is completely located in the hanging wall of the ATF and does not crosscut the major fault [Chiaraluce et al. 2007]. This observation suggests that the ATF may contribute to constrain at depth the size of the synthetic and antithetic seismogenic faults confining their related seismicity.

In Figure 1A we show the earthquakes (grey points) distribution for the 15 years before (1995-2009) the deployment of the TABOO stations: 9273 events with a completeness magnitude of 1.2 (see histogram in the inset). This is the seismicity recorded and located by the INGV national seismic network (available at: http://iside.rm.ingv.it/iside/standard/index.jsp) that in this area was able to generate a completeness in the catalogue below the mean value of M₉ = 1.7 computed for the whole Italian territory [Amato and Mele 2008].

Seismic activity is generally spread over the whole study area in past 20 years (location and focal mechanisms in Figure 1A). The southernmost is the 1997 Colfiorito Mw 6.0 earthquake with its sequence of moderate-magnitude events. Going north we find the 1998 Gualdo Tadino Mw 5.1 and the 1984 Gubbio Mw 5.1 events, respectively. All these earthquakes activated SW-dipping normal fault systems, thus antithetic to the ATF. The comparison of the 1984’s aftershocks distribution with background seismic activity of the area clearly shows how the Gubbio sequence is completely located in the hanging wall of the ATF and does not crosscut the major fault [Chiaraluce et al. 2007]. This observation suggests that the ATF may contribute to constrain at depth the size of the synthetic and antithetic seismogenic faults confining their related seismicity.

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Seismic activity is generally spread over the whole study

<table>
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<th>Year</th>
<th>Mo</th>
<th>Da</th>
<th>Epic.Area</th>
<th>RtM</th>
<th>Nip</th>
<th>Imax</th>
<th>LatM</th>
<th>LonM</th>
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Table 1. Epicentral parameters of the largest historical earthquakes occurred in the study area (from Rovida et al. [2011], and reference therein). The acronyms stand for: Year for the year of the earthquake origin time; Mo is the month of the origin time and Da is the day. Epic.Area is the name of the epicentral area; RtM is the reference of the specific macroseismic study; Nip is the number of the intensity points available for the event; Imax is the maximum intensity value; LatM is the epicentral latitude (macroseismic determination); LonM is the epicentral longitude (macroseismic determination); Io is the intensity; Mwdef is the default moment magnitude and DMwdef is the associated error.
area. We observe a sort of clustering just along a NW-trending sector placed in between the Gubbio and Città di Castello basins. Regarding the historical earthquakes of the area (red squares in Figure 1A), the CPTI11 catalogue [Rovida et al. 2011] reports several events with $M_w \geq 5.5$ (see Table 1) that occurred in the 1000-1917 time-window. Three of these earthquakes (Monterchi, 1352; Umbria–Marche Apennines, 1751; Cagliese, 1781) had $M_w > 6$.

The whole picture related to the historical seismicity seems to be coherent with the datum that the major instrumental seismic activity is observed along the northernmost basins, as well as the higher sedimentary rate that has been attributed to the San Sepolcro one (Pucci and Mirabella personal communication). Most of the historical earthquakes occurred in fact on the northern edge of the studied area, from the hills of Monterchi–Citerna (between San Sepolcro and Città di Castello) to the Tiber Valley and nearby foothills to the Umbria–Marche Apennines (near Caglì); then the other earthquakes are located in the southeast corner of the area (near Gualdo Tadino). We remind here that the epicentral parameters of the largest events listed in Table 1 (e.g. 1352, 1751 and 1781) are derived from high quality studies based on extensive historical research. The low number of intensity data points available for the earthquakes occurred before the 18th century (less than ten to each earthquake, against several dozens to over a hundred and fifty data points available for the 18th and 19th century earthquakes) depends on specific historical circumstances. It is well known that the absolute availability of historical sources varies greatly depending on the period and area under study. At the same time we cannot exclude that further research could lead to an improvement in knowledge. For example some new data on medieval frescoes (see Castelli [2002]) contributed to better characterize the effects of the 1352 earthquake.

In Figure 2 we show a cross section drawn along the strike of the fault system (see section trace in Figure 1B), including the largest historical and the instrumental earthquakes. This comb like picture better highlights the primary remark that no large earthquakes occurred in the central portion of the ATF. Moreover, based on the size of the fault and considering Wells and Coppersmith [1994] relationship between magnitude and rupture length, we define that the average size of an event activating the entire ATF should be around $M_7$. This means that the historical records do not contemplate the occurrence of such an event at least in the past 1000 years. The possible explanation for this are: a) the ATF quake has recurrence time larger than 1000 years; b) the fault is not storing/releasing stress, or c) the ATF is sliding aseismically (creeping). TABOO will help us to understand which is the most likely explanation.

4. The research infrastructure

We show in Figure 1B the actual configuration of the permanent seismic and geodetic stations installed in the study area. This configuration is essentially stable from April 2010. All the instruments are currently integrated into the INGV National Seismic (RSNC) and Geodetic (RING) networks. The data are real-time transmitted to the INGV acquisition systems providing the data infrastructures for continuous data archiving in standard formats and guaranteeing access to data for scientific purposes. The seismological data are available at the Italian Seismological Instrumental and Parametric Databases (ISIDE) portal (http://iside.rm.ingv.it), while considering of the relatively low strain rate characterizing the study area (around 50 nanostrain/year; D’Agostino et al. [2009]), the GPS network is still relatively too young (on average less than 3 years) to produce stable data. In Figure 3 we show and example of a standard TABOO site where seismic and geodetic sensors are co-located.
Regarding the seismological network, we benefit from a European project named GLASS (Integrated laboratories to investigate the mechanics of aseismic vs. seismic faulting), an ERC (European Research Council) Starting Grant (http://www.roma1.ingv.it/laboratori/laboratorio-hp-ht/glass-project) hosted by INGV, to implement the NFO by drilling and instrumenting a series of three shallow boreholes [Collettini and Chiaraluce 2013]. The small box in Figure 1B indicates the boreholes location area, which is zoomed in Figure 4. We selected this area to deploy the array around a deep (5.6 km) existing borehole (Mt. Civitello) drilled in the eighties by Italian National organization for Hydrocarbons (ENI), in order to have data available from the past drilling experience to constrain the local one-dimensional (1D) velocity model for $V_p$ [Chiaraluce et al. 2014]. The three boreholes have a depth of 182 m (BAT1), 204 m (BAT2) and 250 m (BAT3), respectively. Dealing with microseismic activity we decided to instrument the boreholes with 3-component short period seismometers (2Hz) sampling the signal at 500 samples per seconds. The sensors are passive to avoid power within the hole. Each borehole has one sensor at the surface and at the bottom depth, while the deepest one (BAT3) has a vertical array with a sensor every 100 m (0, 50, 150 and 250 m).

Figure 3. A standard installation of the TABOO network (station ATTE). All of the instruments (GPS and broad-band seismometer) send real time data through a Wi-Fi system based on dedicated radio links [Monachesi and Cattaneo 2010]. In the inset we show a picture of our standard electromagnetic antenna.

Figure 4. Zoom of the box reported in Figure 1B of the area where the three shallow boreholes instrumented with short period seismometers are located. The green house is the location of the 5.6 km deep borehole (named Mt. Civitello) while the red square is the location of the seismic and geodetic station ATVO (Monte Valentino). Each (white) column represents the boreholes length (relative scale) with the installed seismometers (black polygons).
We have evaluated the detection capabilities of the whole seismic network by means of a fully empirical procedure. First of all, the background noise of each station was characterized, in terms of Probability Density Functions, by means of the PQLX software [McNamara and Boaz 2010]. In particular, the modal value and the 90th percentile value were taken into account as representative of the stationary noise condition excluding earthquakes and low probability transient noise sources. We computed an empirical magnitude-amplitude-distance relationship for the TABOO area, based on the data recorded by the network in the last 3 years. The analysed amplitude was calculated as the spectral amplitude in a selected frequency band typical of small magnitude events (usually 2-15 Hz). A 3D mesh of source points was set up in the area, and for each point earthquakes of increasing magnitude were simulated; the expected amplitude at each station was compared with the relevant noise level (median or 90th percentile). The lowest magnitude presenting a ratio between the expected amplitude and the noise level above a selected threshold (Th), at a minimum number (n) of stations, is defined as the detection threshold for that point. We set Th = 6 and n = 6, values representing a high possibility of obtaining a well-constrained hypocentral location for the detected event.

Figure 5A and B show the results obtained using the modal noise estimate at 5 and 15 km of depth, respectively. 5C and 5D present the worst-case scenario by using the 90th percentile noise estimate always at 5 and 15 km of depth, respectively. See text for explanation.

Figure 5. Maps describing the detection capability of the seismic network evaluated by means of an empirical procedure. 5A and 5B show the results obtained using the modal noise estimate at 5 and 15 km of depth, respectively. 5C and 5D present the worst-case scenario by using the 90th percentile noise estimate always at 5 and 15 km of depth, respectively. See text for explanation.
Exceptions. Maps A and B in Figure 5 demonstrate that TABOO seismic network provides a very good (i.e. low) detection capability in the sense that we should be able to detect and locate all the events equal and larger than $M_L 0$ occurring within the whole monitored volume.

Then, in Figure 5C and D, we present the worst-case scenario by using the 90th percentile noise estimate. Clearly the magnitude threshold is increased, nevertheless also for the 15 km layer a magnitude threshold with negative values characterizes the inner part of the network, and for the surrounding area the network guarantees a detection capability around $M_L 0.5$. It is evident the contribution given by the 3 borehole stations producing a relative minimum particularly visible in the map of 15 km of depth. However, the good detection capability is not only due to the reduced inter-station distance (mean distance around 8 km), but also to the rather low noise levels, in the analysed frequency band, characterizing the station sites we selected.

One of the reasons to keep under control the minimum detection capability of the seismic network is to investigate possible breakdown thresholds of the earthquake-size distribution towards very low magnitude earthquakes otherwise following the Gutenberg and Richter law [Gutenberg and Richter 1944].

In Figure 6 we report in map view and cross section the events collected during the first three years of monitoring activity (from April 2010 to April 2013). Grey stars represent the events with $M_L > 3.0$ and available focal mechanism solutions.
stations (black triangles) together with the temporary ones (grey triangles) that we deployed in the area for one year and a half (2011-2012), to reoccupy the same sites of the 2000-2001 experiment [Piccinini et al. 2003]. In this way, we will be able in the near future to locate together the new and the old set of data. Moreover, a dense station coverage of the area, even if temporary, allows the collection of data to compute a 3D tomographic model better sampling the volume parameterized by smaller grid spacing.

We detected 19,422 events with \( M_L \leq 3.8 \). The hypocentral locations are preliminary ones obtained with the 1D velocity model proposed for the area by De Luca et al. [2009]. Once the velocity model will be improved we will relocate the seismicity applying also waveforms similarities techniques to retrieve relative locations improving the relative arrival times.

The seismic activity is mainly concentrated along the San Sepolcro-Gubbio alignment similarly to the general picture given by the seismicity of the previous 15 years (Figure 1A). The main difference is that now the number of events is dramatically greater. In the cross section of Figure 6 drawn perpendicularly to the system we can appreciate how the seismicity deepens at low angle toward the E-NE direction mimicking the ATF geometry. The largest event occurred within the study region is a \( M_L 3.8 \) (20100415 01:47 UTC) located nearby the Pietralunga village. A detailed study of this minor sequence highlighted the geometry of the kilometer-scale activates high-angle normal fault segment, synthetic to the ATF [Marzorati et al. 2014]. While the aftershocks pattern and related seismicity migration episodes have been related to fluid discharge processes [Chiara 2012] often observed during larger Apenninic normal faulting sequences (e.g. Colfiorito, 1997; L’Aquila, 2009). All these aspects underline the relevance of studying microseismic activity.

We report in Figure 7 the curve describing the cumulative number of the 2010-2013 events versus time (black line). To better estimate the rate of earthquake production, we declustered the catalogue (using the Reasenberg [1985] approach) by removing the aftershocks sequence following the relatively larger events (grey line in Figure 7). The declustering has been performed by applying the Reasenberg algorithm with the standard parameter setting (see Reasenberg [1985] and Lombardi [2003]) within the ZMAP code [Wiemer 2001] on the absolute catalogues that include \( M_L \) above \( M_c \). The aftershock population is identified by assuming that any earthquake that occurs within an interaction zone of a prior earthquake is an aftershock and is considered statistically dependent on it. Events thus associated are referred to as belonging to a cluster.
and 6). We computed \( r \) by using only the events in the catalogue with magnitude larger than completeness magnitude (\( M_C 0.3 \)) with the intention to minimize the distortion effects when comparing different catalogues retrieved by different seismic networks. We end up with a seismic rate \( r = 23.36 \times 10^{-04} \), a value larger that the one (\( r = 7.30 \times 10^{-04} \)) obtained by Chiaraluce et al. [2009] for the same area with data of a temporary experiment performed in 2000-2001, having a \( M_C = 0.6 \). Thus the difference can possibly be explained with the difference in \( M_C \) between the two catalogues. The value of \( M_C 0.3 \) we obtained (Figure 8) by plotting the frequency distribution of the events for different classes of magnitude is in very good agreement with the map of Figure 5 showing the detection capability of the network.

Physical parameters of the Earth’s crust change before some shallow earthquakes as a response to the earthquake preparatory process [Scholz et al. 1973]. Then, to increase the variety of monitored signals we recently implemented the geophysical network by installing a set of proprietary electromagnetic and geochemical sensors co-located with the seismic and geodetic sensors at four common stations.

The geochemical sensor consists of a Radon detector prototype. The measurement is based on the detection of the alpha decay typical of the decay process of Radon 222 that is part of the Uranium 238 decay chain. Radon entering the scintillation cell decays with a lifetime of 3.8 days in \( ^{218}\text{Po} \), \( ^{214}\text{Po} \), \( ^{214}\text{Bi} \) and \( ^{214}\text{Pb} \). Alpha particles emitted by \( ^{218}\text{Po} \) and \( ^{214}\text{Po} \) interact with zinc sulphide distributed on the detector internal side producing photons. A photocathode, the input of a photomultiplier converts emitted photons in electrons that are multiplied by the diodes in the photomultiplier raising in this way a current signal and then a voltage impulse through a resistor. The number of counts during the acquisition time is proportional to the radon concentration. The detector we have constructed is based on an active monitor powered by a 12V battery charged by a specific power supply connected to the 220V network or to a solar panel. Radon diffuses in a 0.5 l scintillation cell through some holes on a flanged enclosure: between the enclosure and the cell there is some black filtering material in order mainly to prevent other radon short living isotopes from entering the cell and bias the measure (diffusion barrier). The sample frequency of radon concentration is \( 1.39 \times 10^{-4} \) Hz (12 samples in 24 hours). In order to get better insight on the origin of the detected transient signals we installed also a local temperature sensor while other sensible me-

![Figure 9](image-url)
teorological parameters are estimated using available information from public meteorological stations. In Figure 9 we show a time series for few weeks of data collected by MURB station where we can observe that Radon variations are not modulated by meteorological factors. Data from these stations are not yet transmitted to the acquisition centre and this is the succeeding implementation we are working on, to be able to compare the observed behaviour together with all the other monitored parameters.

The electromagnetic active antenna (see inset in Figure 3) is a vertical pipe of the length of one meter. The receiver of very low frequency (VLF) field works on the electric field component in the band that goes from 20 Hz to 20 kHz with a uniform response in the range between 1 and 13 kHz and the sensitivity of 1 µV. The monitoring is done in a continuous way to the sampling frequency of 44,100 Hz. The extension of the band corresponds exactly to that of the acoustic frequencies and the recorded electrical signal will be analyzed performing acoustic spectrograms and sonograms that will be compared with the occurrence of the other transients.

We are now also in the process of installing a series of geodetic corner reflectors (homemade at INGV). Generally space geodesy information by means of SAR interferometry (InSAR) will be integrated with ground measurement techniques (such as leveling, GPS). Through an ESA Category-1 project (Exploring the deformation pattern of the upper Tiber Valley natural laboratory) a series of ERS & ENVISAT SAR images, on ascending and descending orbit, covering a time window between 1992-2010 have been collected and SBAS/IPTA processing are on-going. In addition a network of SAR Passive Corner Reflectors (CRs) will be deployed in the proximity of GPS monuments in order to calibrate SAR velocity map. CRs are designed for the X band SAR of COSMO-SkyMed. The signals will be then processed for gaining higher resolution products moving for example from 80-100 m per pixel to 20-30 m per pixel.

5. Discussions and conclusion

With TABOO we intend to permanently monitor at high resolution a relatively small and actively deforming area by means of state of the art geophysical networks comprising multidisciplinary instruments. We believe that only high-resolution data coming from different disciplines can help us in obtaining a comprehensive picture to comprehend tectonic evolution and fault zone processes.

We have still much to learn about the mechanics of faulting and the complex and possibly inherently scale-dependent processes governing fast and slow deformation processes. Numerous fundamental questions remain unanswered, such as: How did the LANF form and evolve? How do the frictional and rheological properties of fault zones vary in space and time? How do aseismic and seismic slip interact in time and space characterizing the state of stress of active faults? How the stress field is oriented within the upper crust?

We have summarised in the cartoon illustrated in Figure 10 a range of possible deformation behaviours related to misoriented faults (such as the ATF), which will likely be identified and corroborated by the new high-resolution data that we are going to acquire with TABOO. We consider a LANF with fluids (e.g. CO₂) overpressure trapped in the footwall block. Earthquakes can nucleate within or outside the fault core (Figure 10A and B, respectively), possessing different structure and rheological properties. In the first case the fault core has brittle rheology with cataclastic textures and friction coefficient in the Byerlee range (0.6-0.8; Byerlee [1978]). In this case earthquakes may rupture shallow-dipping planes generating moderate to large events. The rupture can initiate on a small (velocity weakening) fault portion where tensile fluid overpressure cannot be sustained [Sibson 1990] and then propagate along the fault plane. In the second case

![Figure 10](image_url). Cartoon showing a schematic sketch of three possible mechanical models explaining the seismic activity and kinematic related to stick slip (earthquakes) and stable sliding (creeping) events occurring within and outside the fault core of a shallow dipping plane. The arrows represent the fluid (CO₂) fluxes. See test for explanation.
earthquakes are located right above the fault core (plane) and they rupture the high angle plane as brittle response of the fault hanging-wall to strain localization and ductile deformation (creeping) occurring on the LANF plane. In this case the LANF fault core may be constituted by highly foliated fault rocks such as foliated phyllosilicate-rich fabrics and associated weakening effects due to fluid-rock interaction (e.g. Zuccale fault core; Collettini et al. [2009]). The last scenario (Figure 10C) includes multiple discrete fault planes and the slip distributed within a wide fault zone possessing different rheological properties. Microseismic events can occur within the fault zone in velocity weakening patches loaded by many factors like: tectonic stress, stress redistribution caused by aseismic slip on adjacent volumes, coseismic slip of nearby earthquakes, fluid pressure fluctuation and/or pore pressure relaxation. Most of the LANF should slip a-seismically or creep because embedded in velocity strengthening materials. While the microseismic events occurring in the volume may rupture fault planes with different geometries depending on the orientation of the local stress field. Due to the poor knowledge we have on the dynamic rupture propagation we then cannot exclude that a rupture nucleating on a minor well oriented asperity may evolve in a large rupture (e.g. seismic event). We remind here that all these scenarios do not explain the origin of such shallow faults mainly if we suppose that they did not rotate with time [Smith et al. 2011].

With TABOO we want also to understand the seismogenic potential of the ATF and therefore contribute to the seismic hazard assessment of the area. The collected information on the geometry and physical properties of the fault will be useful to elaborate ground shaking scenarios adopting diverse slip distributions and rupture directivity models.

Another important aspect regards the study of the physics of faulting and earthquake preparatory phase and we want to approach these issues investigating the occurrence of transients signals that we define here as the occurrence of space-time variations of elastic properties of the rocks and/or short lived and impermanent signals occurring in the solid crust, spring waters, atmosphere and so on. The ambitious challenge is the observation at small scale of changes in the physical parameters describing the crust during the earthquake preparatory process (e.g. precursory phenomena).

One of the most famous experiments worldwide supporting long-term earthquake research projects to better understand the earthquake process and to provide a scientific basis for earthquake prediction is the Parkfield (California, US) earthquake experiment, a section of the San Andreas fault [Bakun and Lindh 1985]. The geophysical instruments operated at Parkfield by the Geological Survey from 1985, have been designed to monitor tectonic processes leading up to one expected earthquake in the following few years and to record the strong shaking and crustal deformation that will result from it. To this end a heterogeneous configuration of instruments has been deployed to recover seismic, deformation, electromagnetic and fluid related signals. After 30 years of investigations devoted to such ambitious objectives, numerous scientific advances have been gained along the way. This is the area where the high-quality observation derived from the dense seismic network together with the implementation of innovative earthquakes location algorithms [Waldhauser and Ellsworth 2000] allowed an extremely high-resolution image of the fault structure [Schaff and Waldhauser 2005]. Looking at these earthquakes nucleating on the San Andreas fault at Parkfield, some of them have been observed to occur as repeating ruptures of discrete patches on the fault surface (repeating earthquakes; Cole and Ellsworth [1995]) and along concentrated streaks on creeping fault sections, northwest of Parkfield [Rubin et al. 1999]. Important improvements have been achieved also concerning fault-zoned fluids and how variations in fluid pressure may affect the timing of earthquakes [Miller et al. 1996]. Lastly, the $M_W$ 6.0 2004 earthquake that occurred at Parkfield is probably the best-recorded event ever. Following Bakun et al. [2005], the lack of obvious precursors demonstrates that reliable short-term earthquake prediction still is not yet achievable. At the same time Parkfield still remains the major battleground over earthquake prediction and between the concepts of repeatability and variability of earthquakes.

All these major topics largely justify the need for modern multisensory networks implementations and the work we are carrying on to produce high-resolution observations that can be sustained in the long term.

We need to generate a high-resolution earthquakes catalogue to analyse the seismicity pattern (e.g. b-value and rate of production) characterising the events related to the ATF geometry (misoriented) in respect to the one characterising the high angle faults (well oriented). We need to investigate the frequency content and the source parameters of these two groups of events to evaluate if there are systematic differences underlying different mechanical properties. We need to analyse the kinematic of the events studying the focal mechanism solutions to investigate if there is re-orientation of the stress field approaching the ATF plane. Focal mechanism solutions based on the availability of detailed 3-dimensional velocity models at the hundreds of meters scale will be computed through waveforms modelling also for
smaller events (M > 3.0). Velocity models together with the known principal discontinuities (e.g. ATF plane) will be used as starting models for tomographic studies.

Additional insights will be provided by the availability of the dense GPS network. The deformation velocity gradient we are starting to observe through the ATF system [Vadacca et al. 2014] will be used to constrain the interseismic deformation by 2D-3D finite element modelling. This implies the investigation of the effects of different locking depths for the ATF, the role of synthetic and antithetic segments and the effects of the lithology. Subsequently through a block modelling approach we can measure the fault coupling. The imaging of the ATF deep structure obtained from seismic profiles will allow us the modelling of the ATF plane as a complex rough surface to understand where the stress accumulations are located and the interseismic coupling changes. The preliminary results obtained show for the first time that the observed extension is mainly accommodated by interseismic deformation on both the ATF and antithetic faults, highlighting the important role of this LANF inside an active tectonic contest [Vadacca et al. 2014].

Finally, it is important to perform the majority of the analysis with automatic procedures. We already experienced automatic procedures for generating high-resolution catalogues of aftershocks sequence (e.g. L’Aquila 2009) reaching a completeness magnitude of M0 = 0.6 [Valoroso et al. 2013, and reference therein]. This means having the availability of tens of thousands of earthquakes including repeaters and allowing the researchers to concentrate on the observational aspects.

To this regard we are working on the possibility of transmitting all kind of data to the acquisition centre to be able to visualize the time series all together. In this way we will be able to make inferences basing on multidisciplinary data possibly in quasi-real time. This is our meaning of road to integration to gain advancement on fundamental aspects related to the physics of faulting. In doing this we hope to form a new generation of scientists able to properly integrate data coming from different disciplines.

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